## **Consensus and Formation Control for Multi-agent Systems**

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**Abstract** – The key features of Multi-Agent Systems (MAS) are communication, coordination, and collaboration, by which the agents can achieve a common (and possibly difficult) goal in a more effective and efficient way. Three main topics within the realm of MAS are consensus, flocking and formation control. Cooperating processes often require agents to reach a consensus, which is the fundamental problem in MAS. Flocking (or swarming) is a self-organizing behavior originated from small-size animals with lower intelligence, which enables the emergence of swarm intelligence to improve the whole system survivability and competitiveness. Formation control generally aims to drive the agents to achieve a desired formation, scalable and/or changeable. In this talk, modeling analysis and design of a variety of distributed schemes for consensus and formation control are introduced. Simulations and experimental examples are provided to demonstrate the potential of the proposed new design techniques.



**Prof. Peng Shi** received the PhD degree in Electrical Engineering from the University of Newcastle, Australia, the PhD degree in Mathematics from the University of South Australia, the Doctor of Science degree from the University of Glamorgan, UK, and the Doctor of Engineering degree from the University of Adelaide, Australia. He is now a Professor at the School of Electrical and Electronic Engineering, and the Director of Advanced Unmanned Systems Laboratory, at the

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